



## Applications of sensors for urban air quality monitoring

Christoph Hueglin

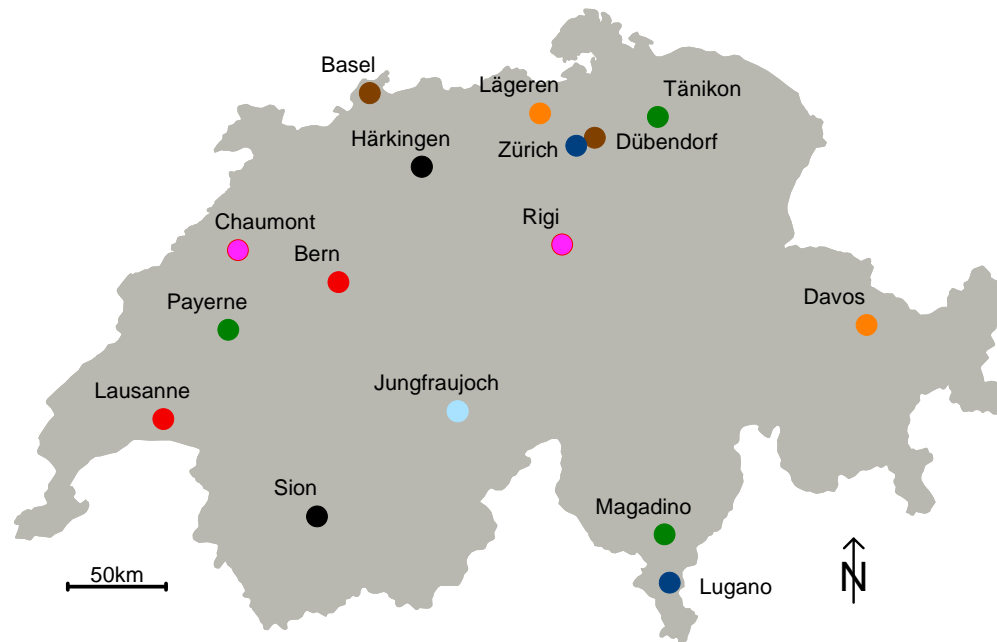
Empa, Swiss Federal Laboratories for Materials Science and Technology

Source: Olga Saukh, ETH Zurich, OpenSense project

# Outline

- Motivation: Why sensors for air quality measurements ?
- Challenges: Assurance of data quality  
Sensor deployment  
Data analysis / modeling
- Summary

# Air Quality Monitoring Today – e.g. Swiss National Air Pollution Monitoring Network



- |                     |                       |
|---------------------|-----------------------|
| ● Urban, kerbside   | ● Rural < 1000 m asl. |
| ● Urban, background | ● Rural > 1000 m asl. |
| ● Rural, motorway   | ● Forest              |
| ● Suburban          | ● High-alpine         |

Monitoring networks provide reliable and accurate information about air quality at **representative sites**

Approach suitable for

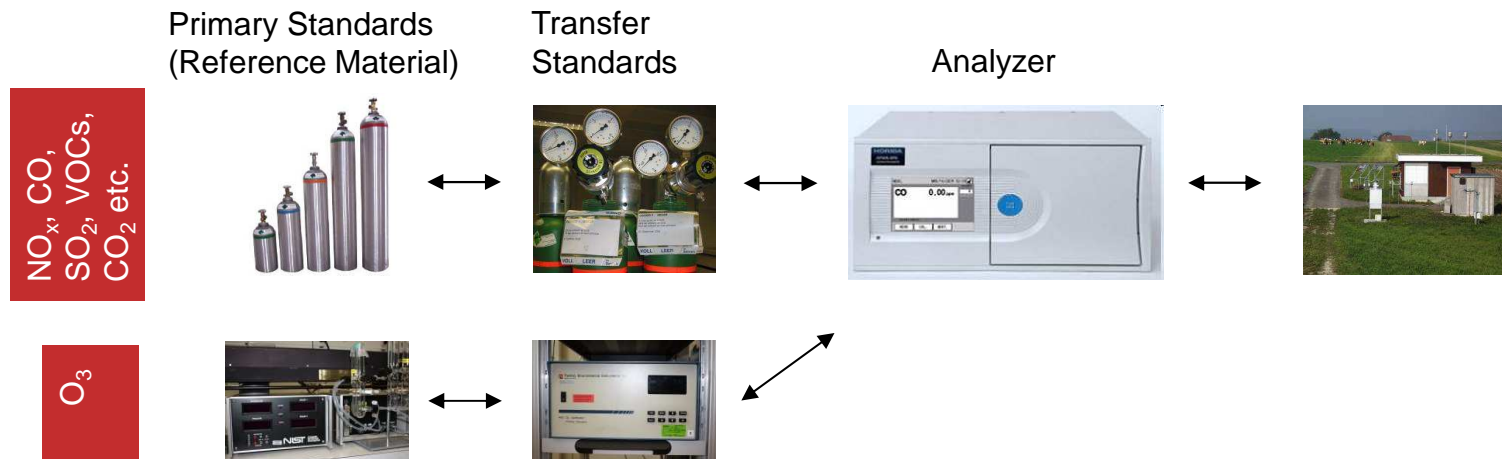
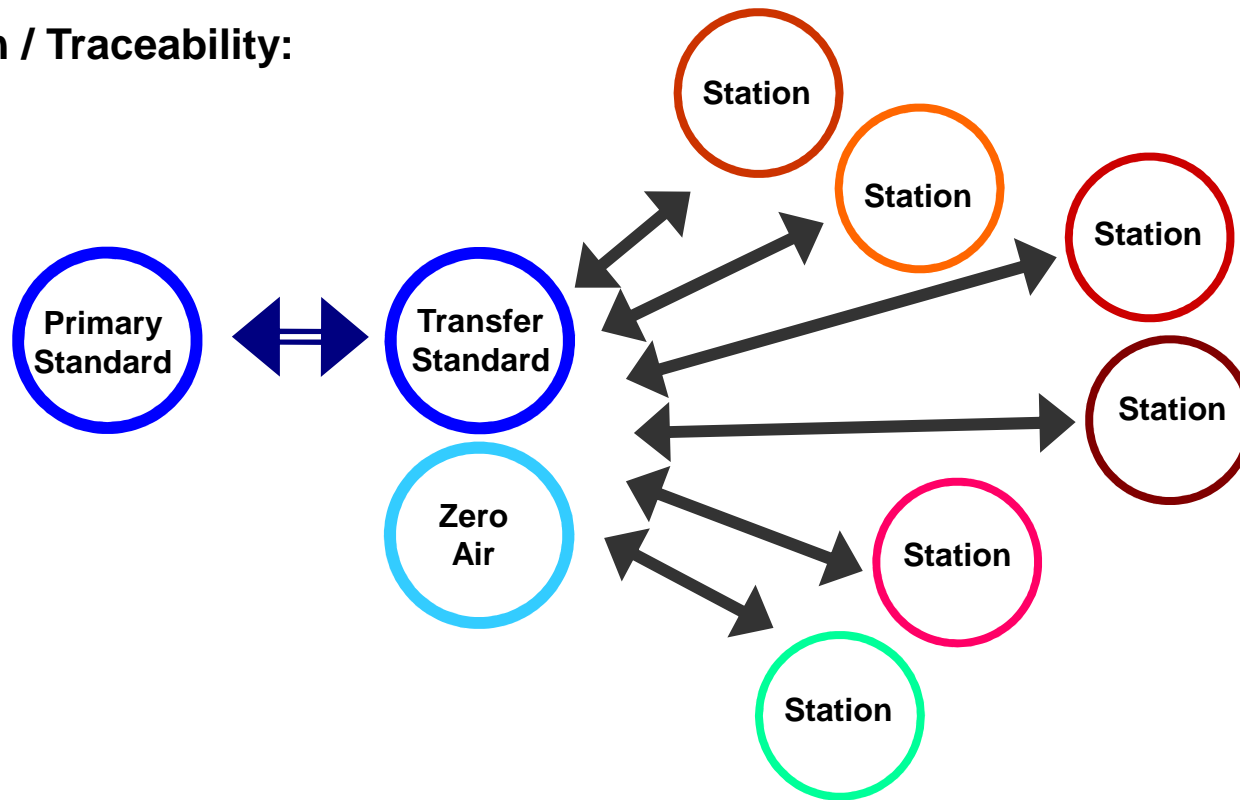
- compliance measurements
- assessment of temporal trends
- action planning
- ...

Approach not ideal for

- assessment of spatial variability at **small scales** (e.g. urban scale)
- exposure assessment / health effects studies

# Assurance of data quality in «traditional» Air Quality Networks

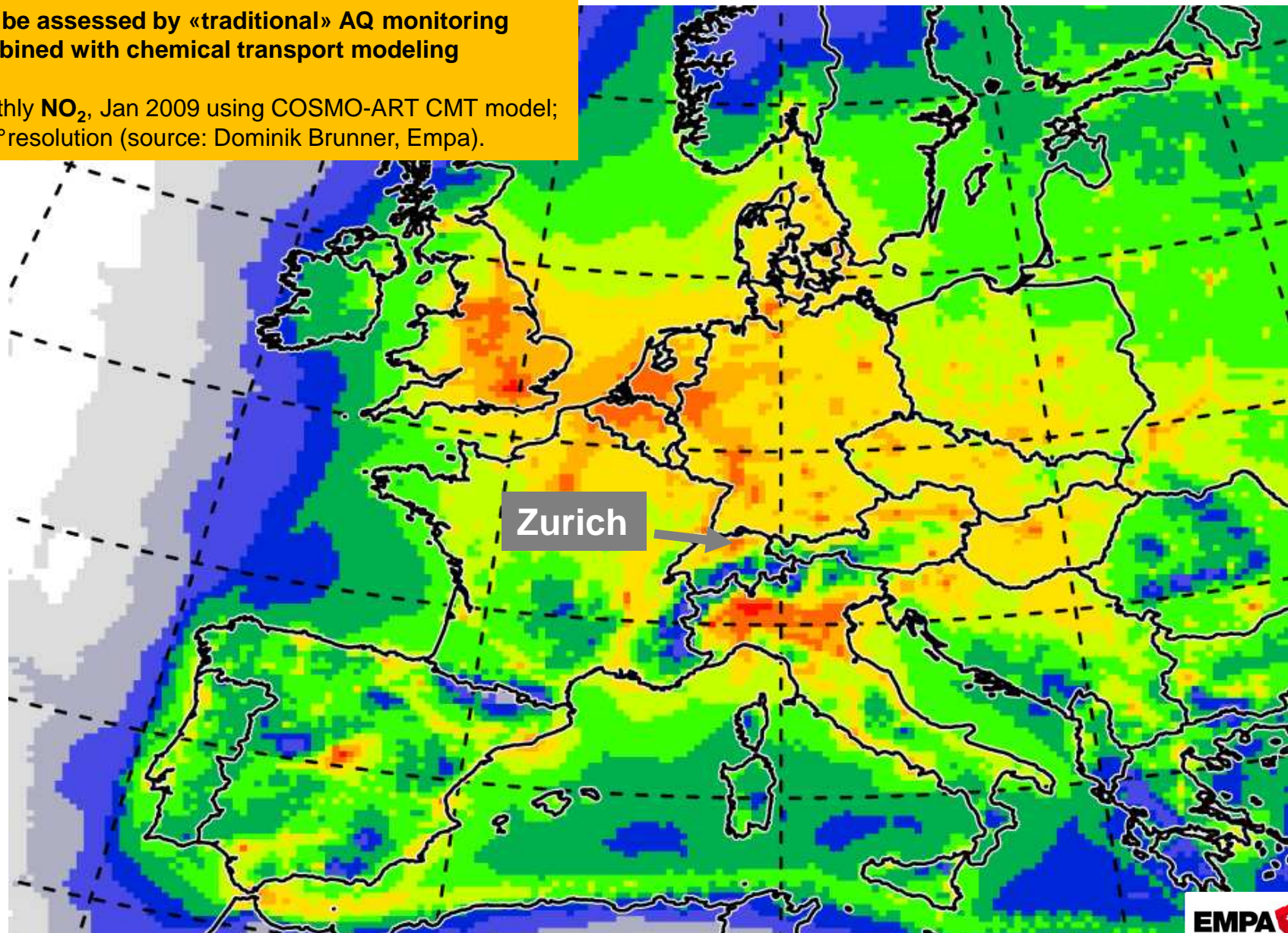
## Calibration / Traceability:



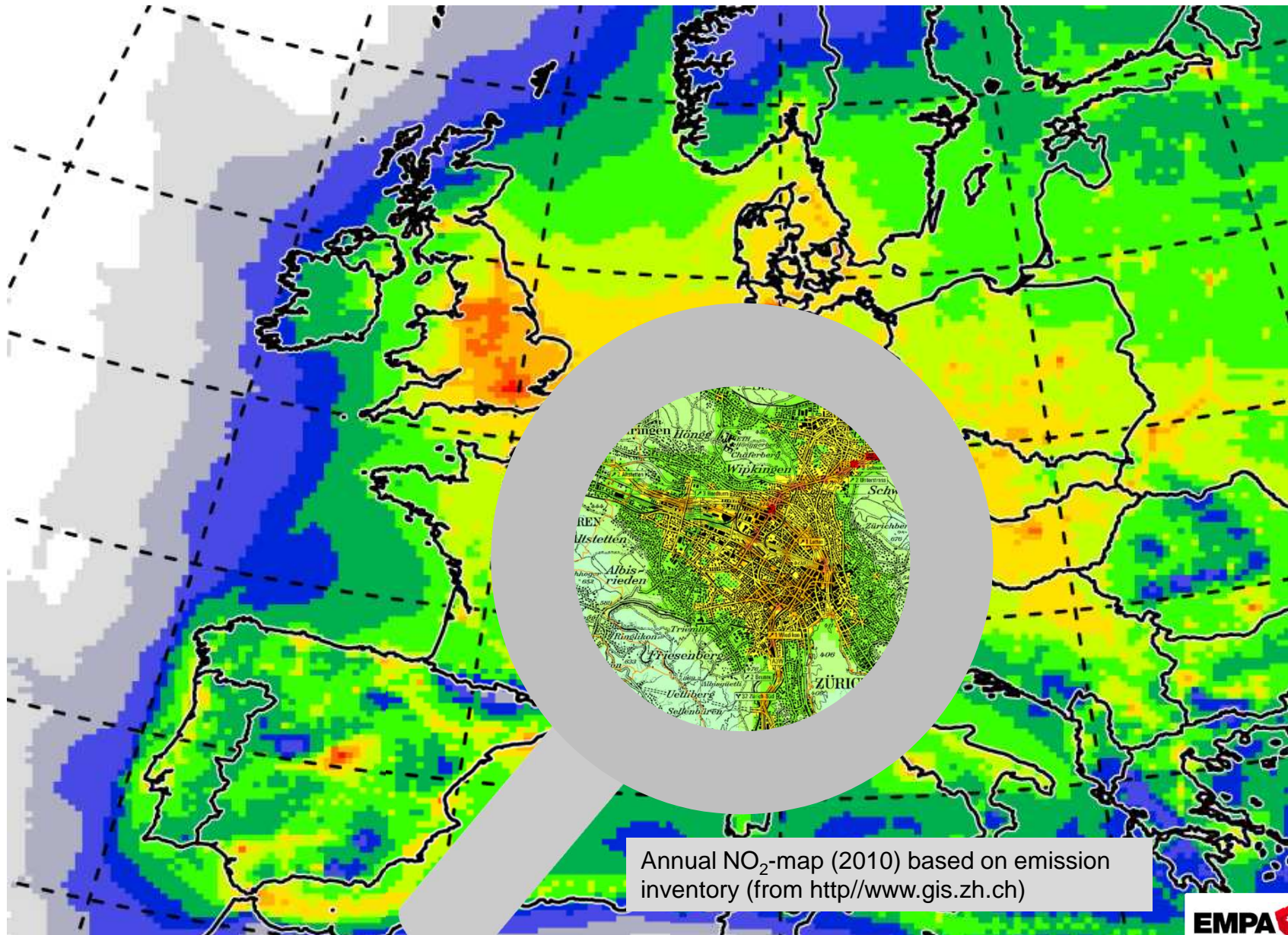
## Spatial variability of Air Pollutants – mesoscale/regional scale

Can be assessed by «traditional» AQ monitoring combined with chemical transport modeling

Monthly  $\text{NO}_2$ , Jan 2009 using COSMO-ART CMT model; 0.17° resolution (source: Dominik Brunner, Empa).



# Spatial variability of Air Pollutants – urban scale?

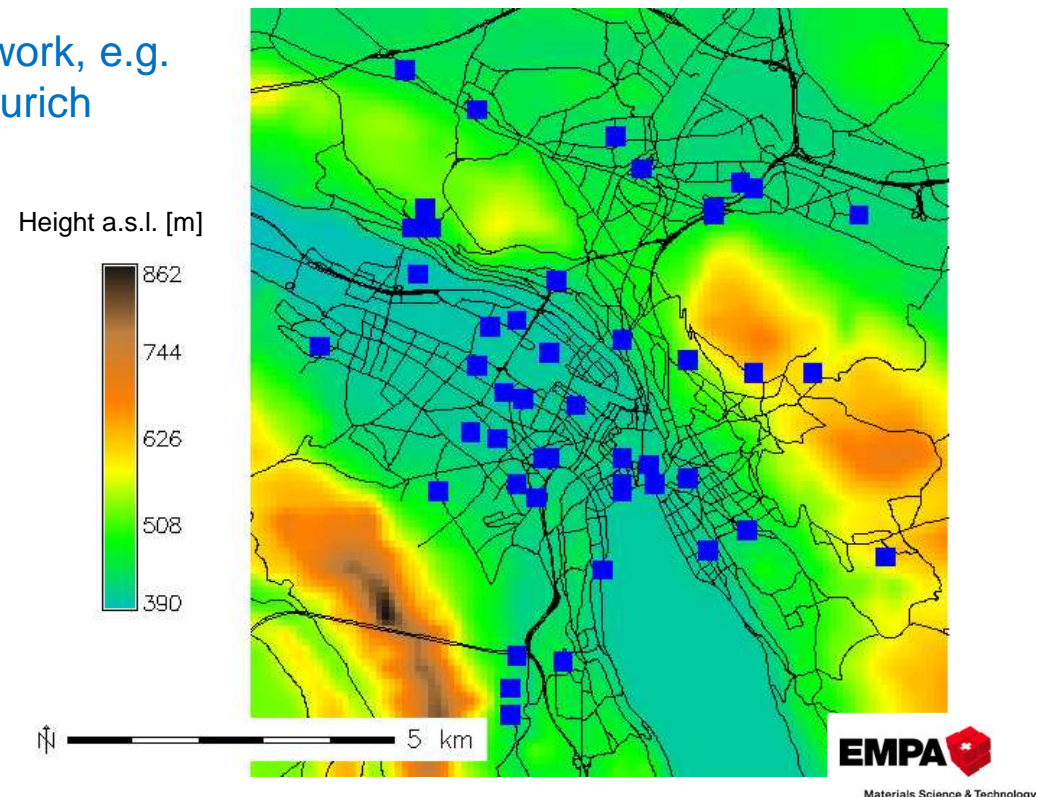


## Spatial variability of Air Pollutants – urban scale

Models for estimation of spatial variability of air pollutants at urban scale with good temporal resolution (e.g. hourly)

- are hardly available
- would be important for detailed personal exposure assessment
- **Sensor Networks** could be a solution

- hypothetical Wireless Sensor Network, e.g. 50 low cost sensors deployed in Zurich



- Are sensors for this application available ?
- What about data quality of sensors ?
- How to use them (deployment, calibration and QA/QC in general) ?
- How to derive spatial information from point measurements (air pollution maps) ?



# SENSORS EXIST - EXAMPLES

**Electrochemical Gas Sensors:** measure the concentration of a target gas by oxidizing or reducing the target gas at an electrode.



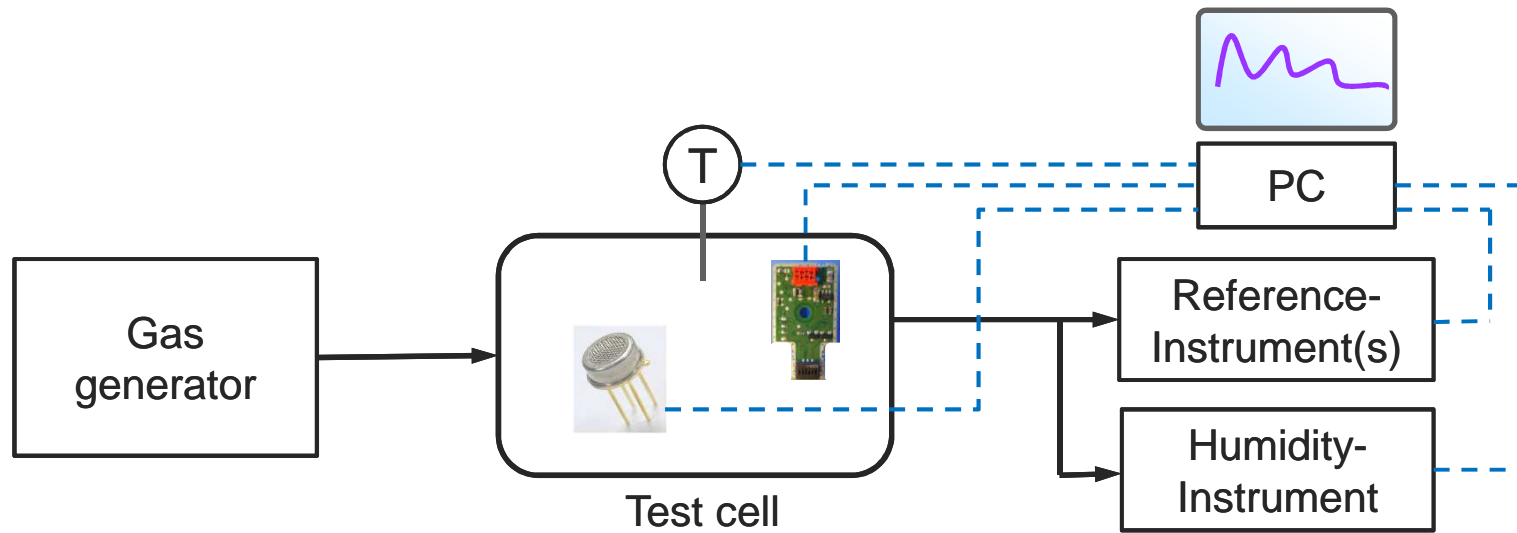
**O<sub>3</sub> - Metal Oxide Semiconductor Gas Sensor:** tiny chip heated up to several 100°C, which also contains a thin layer of a semiconducting metal oxide. When a specific gas is present, the electric conductivity of the semiconductor is altered.



**Particulate Matter:** miniature diffusion size classifier instrument for nanoparticle measurement (small but not low-cost), sensors based on light scattering (low-cost)



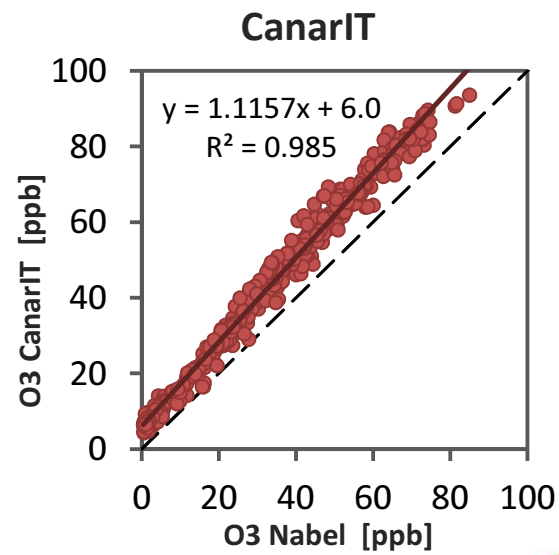
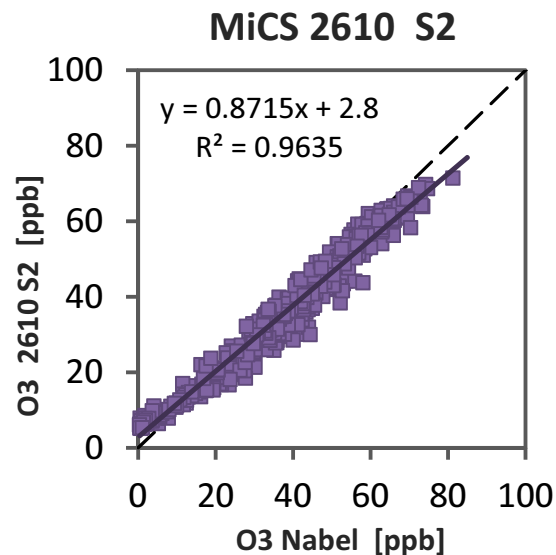
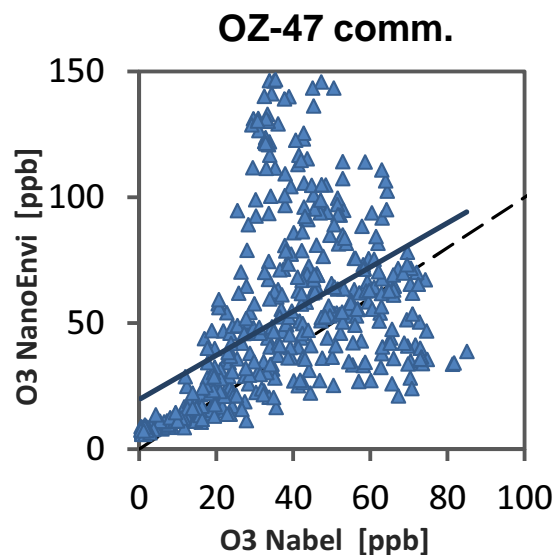
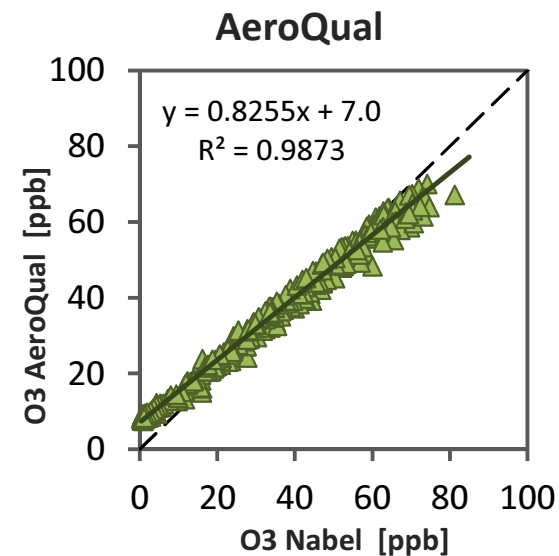
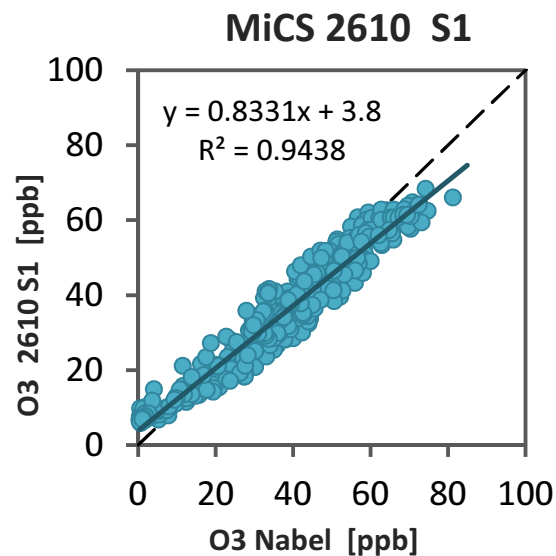
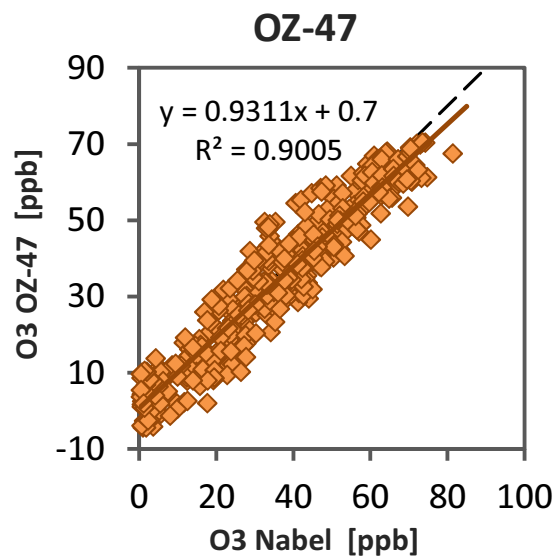
# Assessment of Sensor Performance - Tests in the Lab.



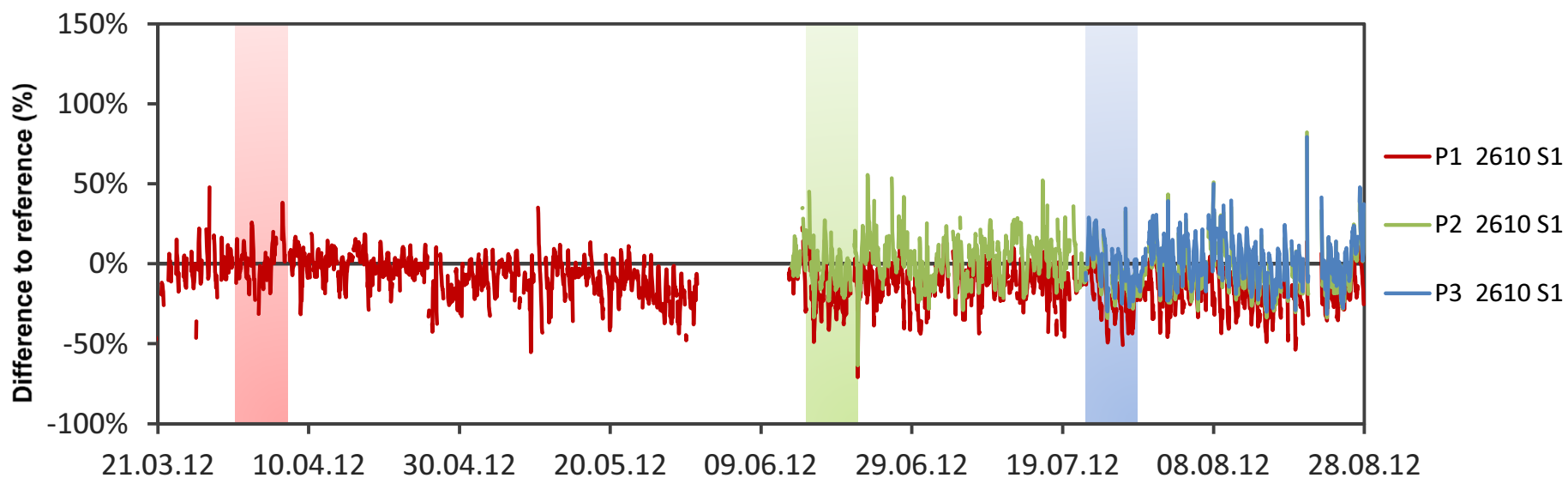
# Side by side measurements at fixed (reference) site in Duebendorf



# Side by side measurements of O<sub>3</sub> using sensors and a reference monitor (TEI 49i) at Duebendorf (hourly values 31.07.12 – 27.08.12)



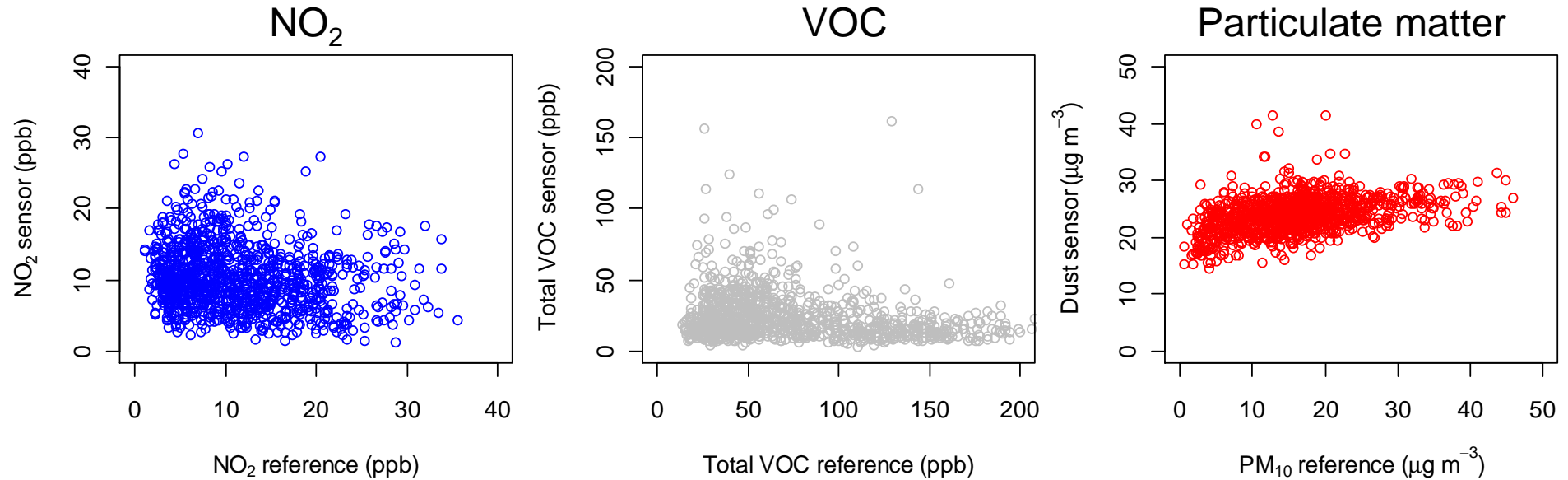
## Comparison of an MiCS 2610 O<sub>3</sub>-sensor with a reference monitor (TEI 49i) at Duebendorf site



- Periodic re-calibration required (here  $\approx$  every 2 month)

# Other air pollutants – Low-cost sensor data vs. reference instruments

Duebendorf, 09.08. – 01.09.2012

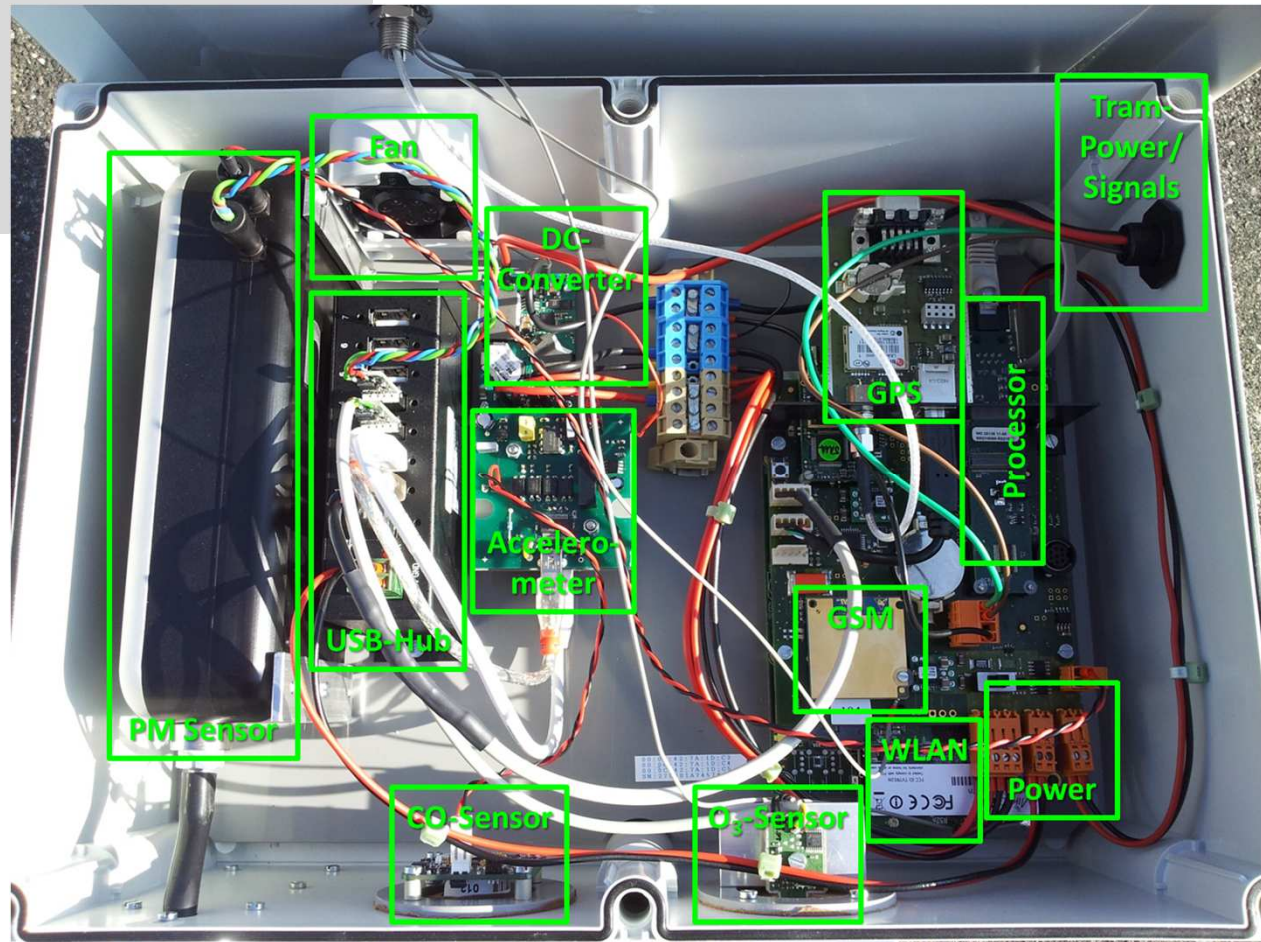


- Data quality of these sensors not sufficient for ambient air quality applications !

## Deployment example – OpenSense project (ETH Zurich)

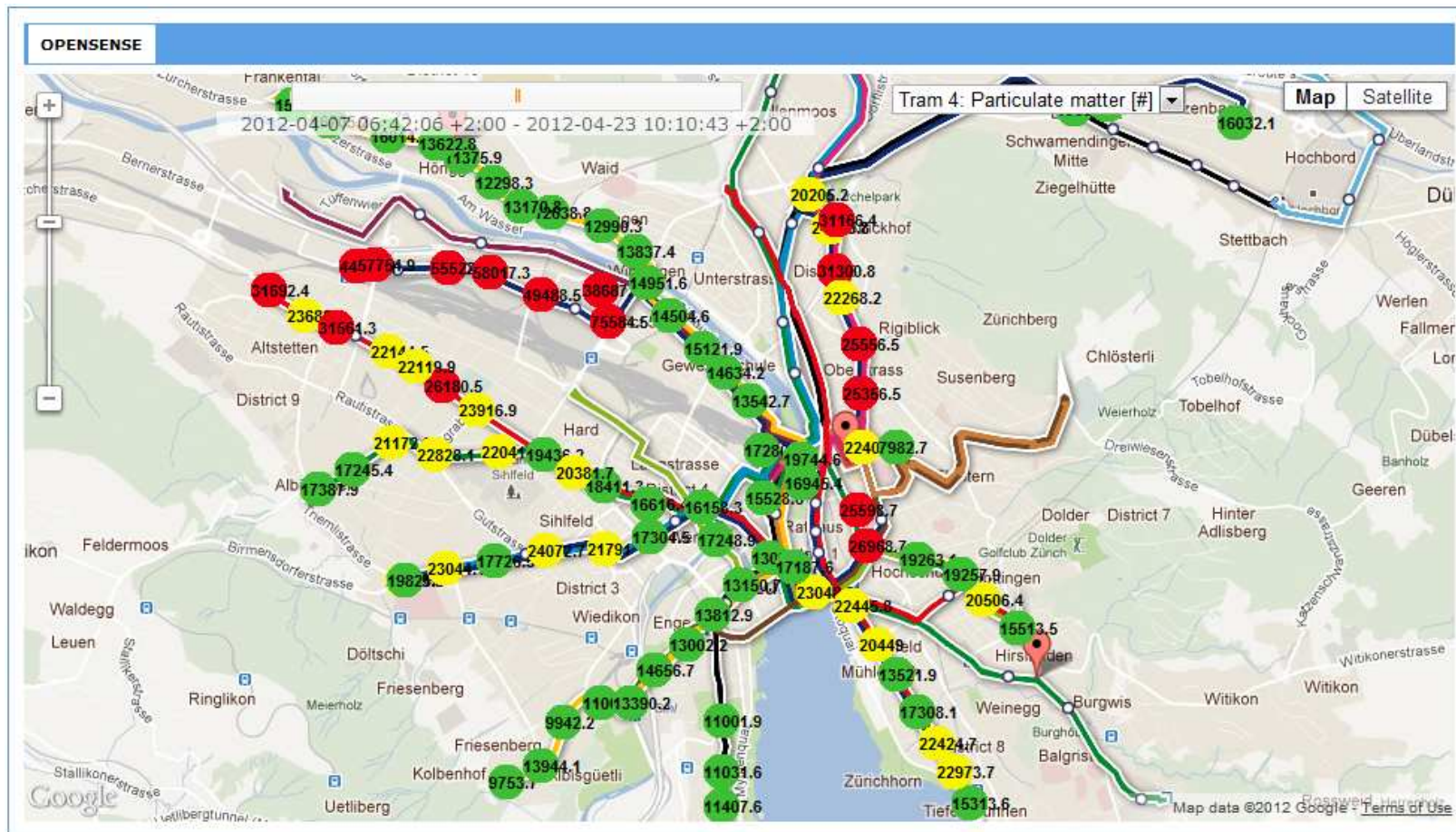


- Currently 5 stations (end 2012: 10 stations)
- Sensors: O<sub>3</sub>, CO, particulate matter (PM), temperature, humidity, accelerometer
- GPS
- Communication: WLAN, Ethernet and GSM
- External power supply





# Deployment of mobile sensor nodes – Which routes to select ?

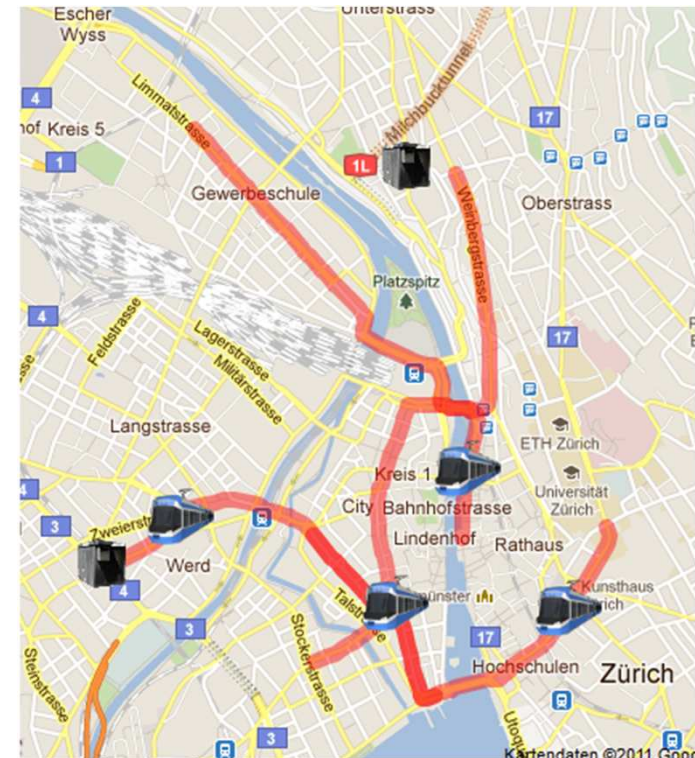
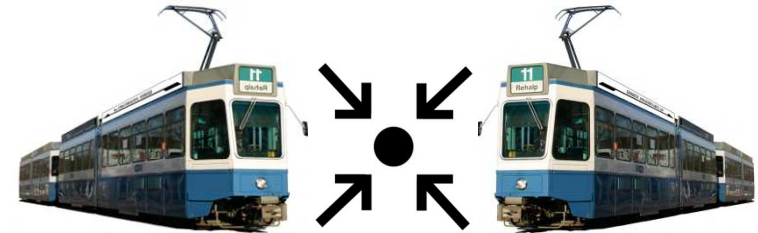


**Spatial coverage is one aspect !**

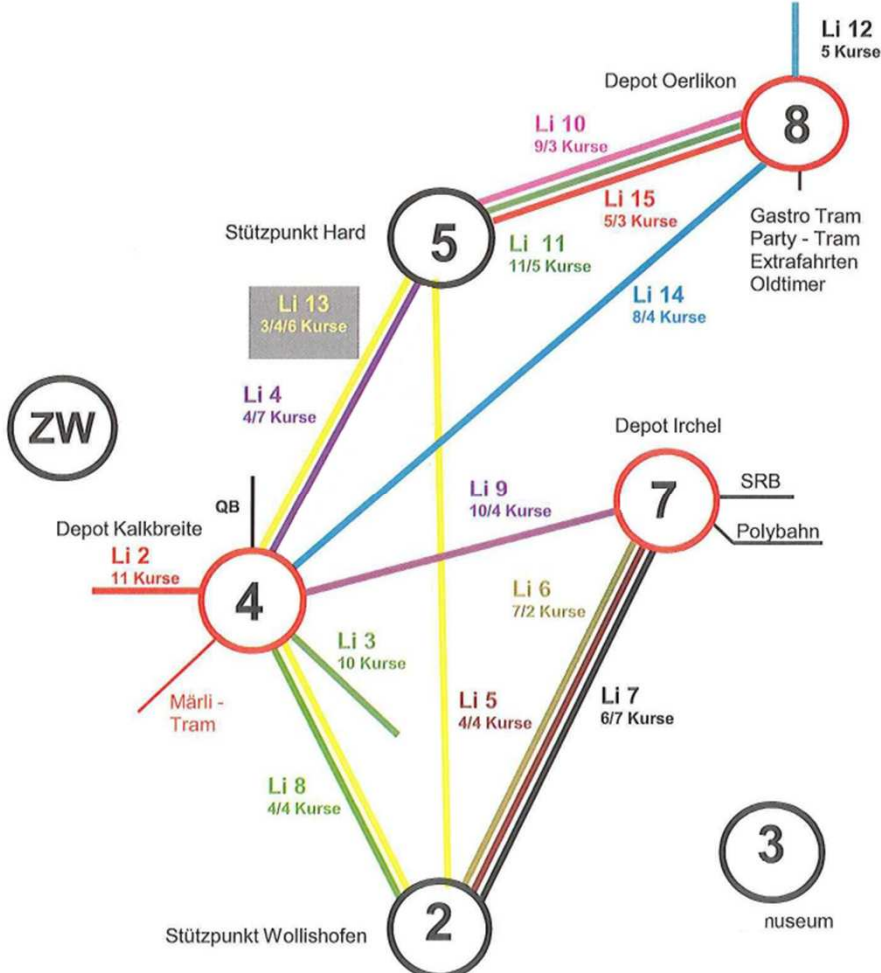
Possibilities for sensor calibration and testing is another aspect !

## SENSOR CHECKPOINTS

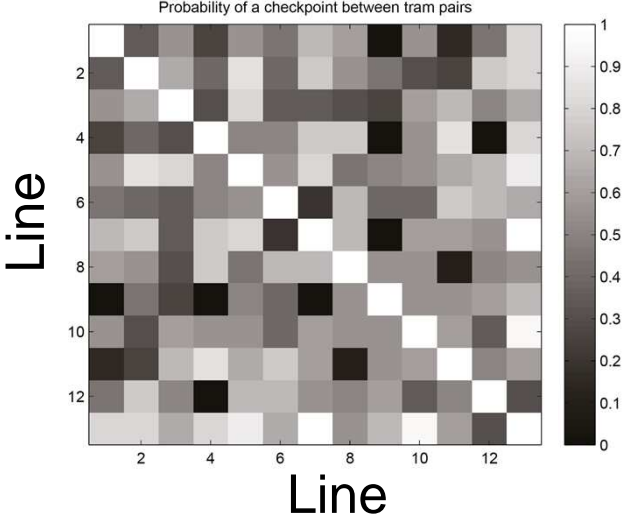
- Two vehicles make a **checkpoint** if the distance between them is below a certain threshold.
- **Checkpoints** are used for:
  - Relating measurements in space and time
  - Comparing sensor readings and sensor calibration
  - Recognizing faulty sensors
- Types of checkpoints:
  - Between two nodes
  - Between node and a reference station



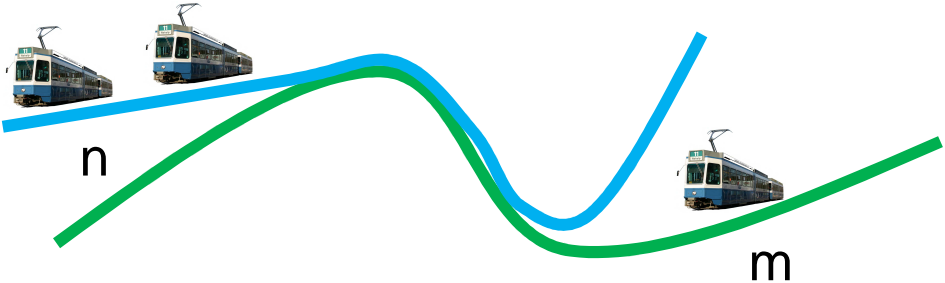
# ROUTE SELECTION UNDER UNCERTAINTIES



Pairwise checkpoints



$$P(\text{ckpt}_{nm}) = 1 - (1 - p)^{nm}$$



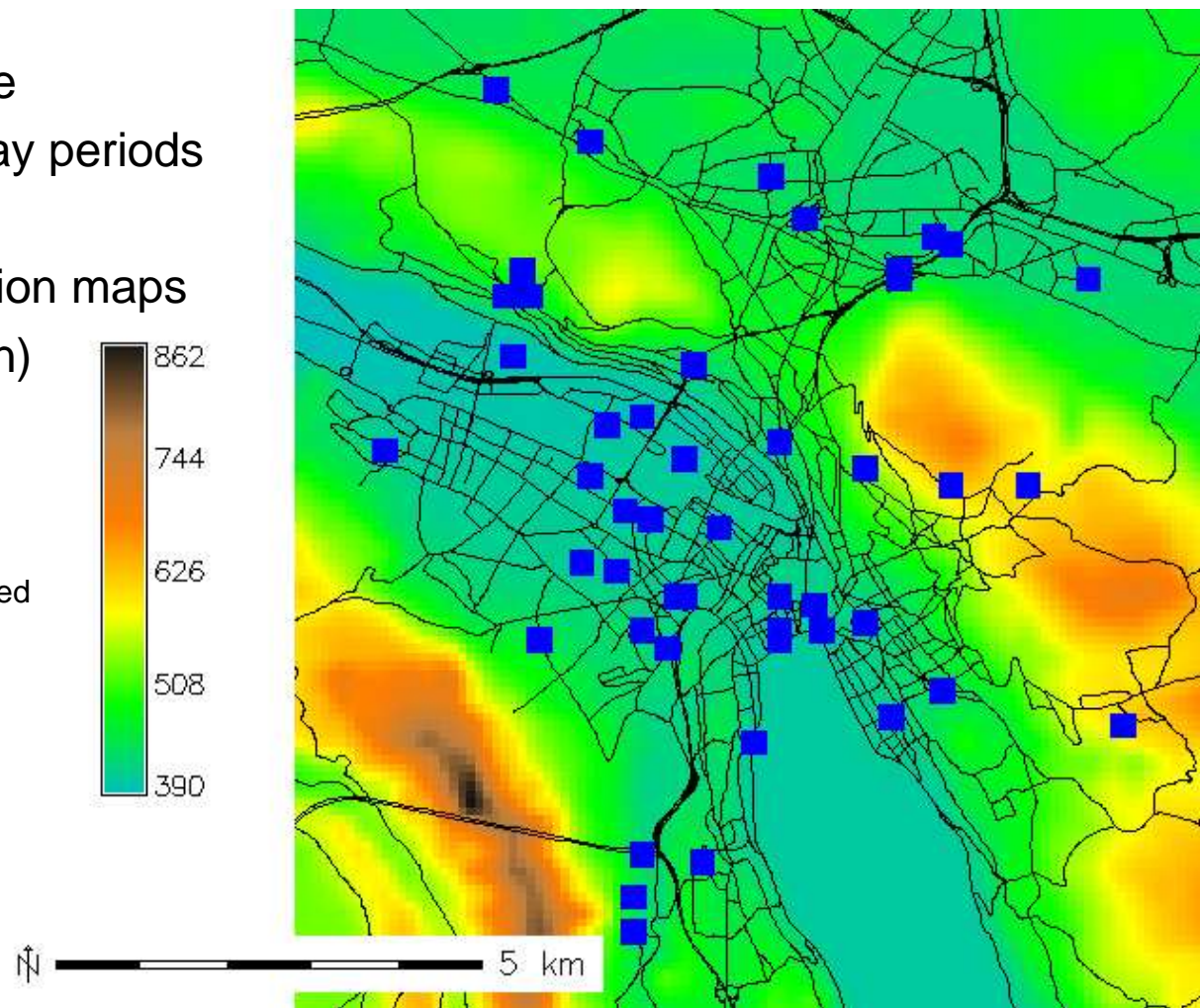
# Research Challenge

**Calibration & testing of sensors deployed in networks**

**(e.g. how to assure data quality in mentioned hypothetical network of 50 fixed sensors in Zurich?)**

# NO<sub>2</sub>-measurements in Zurich using passive samplers

- 50 NO<sub>2</sub> - passive sampler tubes deployed
- Measurement of average concentration over 14 day periods
- Estimation of NO<sub>2</sub>-pollution maps (14-d temporal resolution)
- Barmpadimos & Hueglin, Environ. Sci. Technol. (2012) submitted



## Estimation of 14-d NO<sub>2</sub>-pollution maps – Data

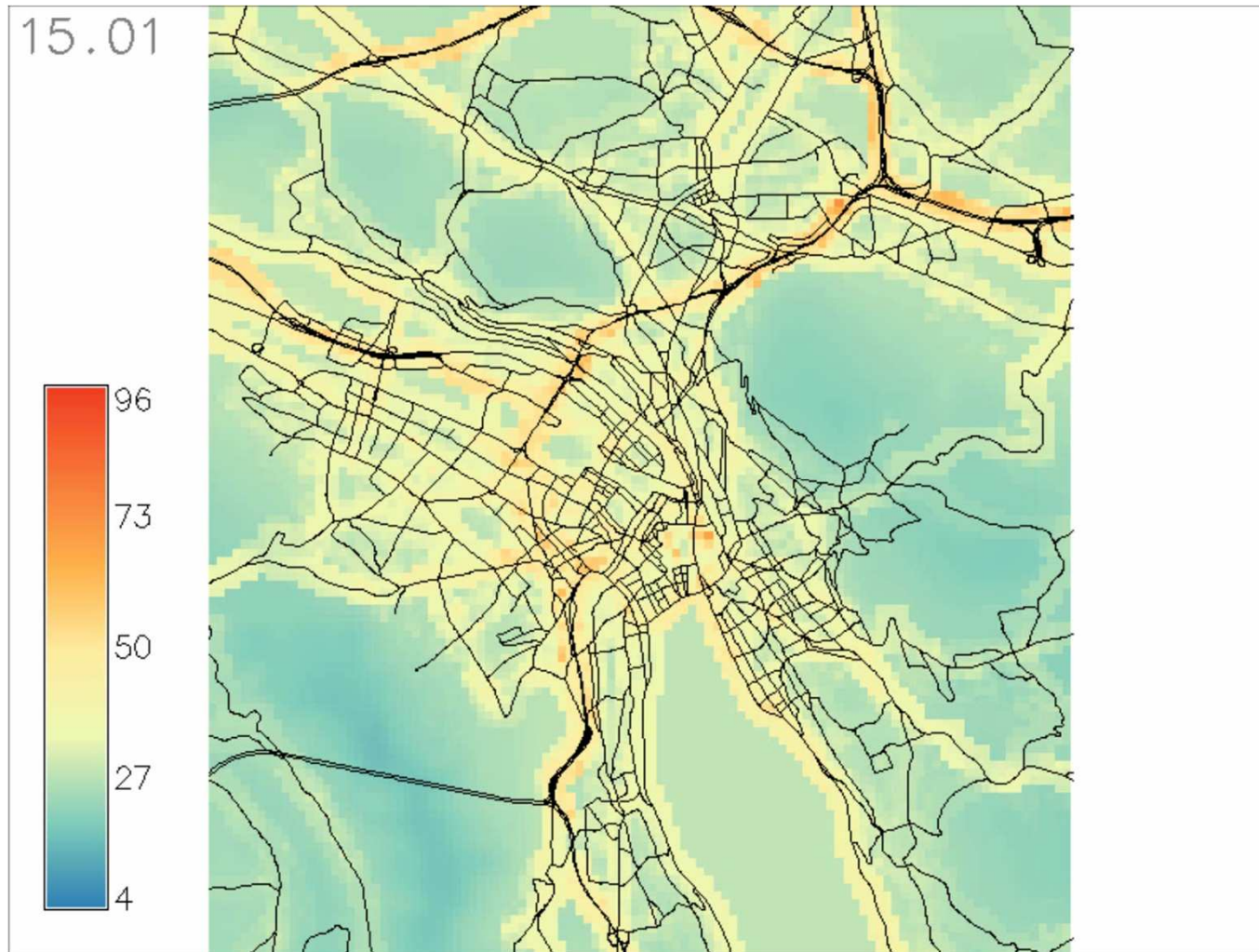
- NO<sub>2</sub> measurements at 49 sites in Zurich (Umwelt und Gesundheit Zürich). 14-d mean concentrations for von 2008
- Landuse data (100m x 100m grid cells)
  - Traffic density (number of vehicles day<sup>-1</sup>)
  - Total length of streets in grid cell
  - Topographic height
  - Population density
  - Number of buildings
  - Total number of building floors
  - Number of buildings using fuel oil or gas for heating
  - Number of jobs in grid cell
  - ...

## Estimation of 14-d NO<sub>2</sub>-pollution maps – Method

- Land use regression (LUR)
- e.g.  $\ln(NO_2) = f(\text{Traffic}) + g(\text{population density}) + \dots$
- $f, g$  etc. are smooth non-parametric functions (Generalized Additive Model, GAM)
- Separate model for each 14-d period estimated
- Automated variable selection
- 10-fold cross validation
- see Barmpadimos & Hueglin *Environ. Sci. Technol.* (2012) submitted

# Estimation of 14-d NO<sub>2</sub>-pollution maps – Results

**2008**





## Summary

- Low-cost sensors offer unique possibilities for assessment of spatial variability of air pollutants on small scales (e.g. urban environments)
- For some air pollutants suitable low-cost sensors are available (e.g. O<sub>3</sub>),
- for others probably not
  - Sensitivity and selectivity are issues
  - Room for improvement - New sensing technologies (COST action TD1105 EuNetAir)
- Assume sensors are available: Novel concepts for calibration and testing of deployed sensors (QA/QC) are needed
- Combination of sensor data and landuse (GIS) data allow estimation of pollution maps in near real-time
- No need to play sensor networks against «traditional» AQ networks (near future / mid-term: sensor networks as a valuable complement)

# Thank you!

## Acknowledgements

- Iakovos Barmpadimos, Beat Schwarzenbach (Empa)
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